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User Manual For UAV PPK Solution

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Revision History

Version	Revision Date	Change summary
1.0	20180928	Initial Release
1.1	20181108	Add position status in processed result
1.2	20190617	Change BX316R to BX306, add RTK option in
		section 6.2.2
1.3	20200513	Minor updates; change 40pin external cable to 20pin
		external cable
1.4	20201022	Remove RTK option tab, add ViewPPK tab, update
		GeoPix interface and ephemeris options.



Table of Content

Re۱	isio/	n History1
Tab	ole o	f Content2
1.	Intr	oduction4
2.	Hai	rdware Connection5
2	.1	Power Supply5
2	.2	EVENT Connection5
2	.3	Connection Diagram7
3.	Sof	tware Configuration
3	.1	Base Station9
3	.2	Rover on UAV10
	3.2	.1 EVENT Configuration10
	3.2	.2 Rover Configuration11
4.	Dat	a Quality Check12
5.	Dat	a Download14
6.	Ge	oPix User Guide17
6	.1	Introduction of GeoPix17
6	.2 G	uide for GeoPix18
	6.2	.1 Set Working Directory and Import Pictures
	6.2	.2 Import Base Data and Rover Data19
	6.2	.3 Data Processing22
	6.2	.4 View processed results
7.	Ter	minology27

List of Tables

ble 1 MARKCONTROL10



List of Figures

Figure 2.1 Connect power cable to the DC port of BX306	5
Figure 2.2 Hot shoe adapter and hot shoe cable	5
Figure 2.3 Connect hot shoe adapter to the camera	6
Figure 2.4 Outline of the 20pin external cable	6
Figure 2.5 Connect hot shoe connector to the EVENT connector	6
Figure 2.6 Connection diagram of Tersus UAV PPK Solution	7
Figure 2.7 Recommended installation of AX3705 helix antenna on the UAV	8
Figure 4.1 Check satellites information using AX3705 antenna13	3
Figure 4.2 Check satellites information using AX3703 antenna13	3
Figure 5.1 Select serial port and download speed14	4
Figure 5.2 Select download path1	5
Figure 5.3 Download data in progress1	5
Figure 5.4 Data download is completed16	6
Figure 6.1 TersusGeoPix in the Start menu17	7
Figure 6.2 Main interface of Tersus GeoPix18	8
Figure 6.3 Select a folder for working directory19	9
Figure 6.4 Select base data and rover data without base position20	0
Figure 6.5 FRD description22	1
Figure 6.6 Select base data and rover data with base position22	2
Figure 6.7 Click RUN to start data processing22	2
Figure 6.8 Geotagged Result List23	3
Figure 6.9 Geotag finished23	3
Figure 6.10 Check the coordinate information of the tagged pictures	4
Figure 6.11 Information in ppk.txt file2	5
Figure 6.12 Positioning results of the GNSS post-processing	6
Figure 6.13 The location information of the EVENT moments	6



1. Introduction

Tersus UAV PPK solution includes BX306 PPK Receiver, AX3705 Helix Antenna or AX3703 GNSS Aviation Antenna and Tersus GeoPix Software. BX306 PPK Receiver supports multi-constellations and dual-frequencies. It has in-built 4GB memory (eMMC) for GNSS observation data recording. Very small and light AX3705 Helix Antenna and AX3703 GNSS Aviation Antenna are designed for UAV applications.

Tersus GeoPix integrates the functions of GNSS observation post processing, Event Mark interpolation and geotagging in EXIF. By clicking one button after inputting all necessary data, the software generates the result which can be used as direct input for image processing software. Tersus GeoPix is part of Tersus Tool Suite which can be downloaded from the official website: <u>https://www.tersus-gnss.com/software</u>.

The general process of this solution is as follows:

First, mount AX3705 helix antenna or AX3703 GNSS aviation antenna and BX306 PPK board on the drone, connect camera hot shoe to Event Mark port of BX306 for camera shutter synchronization. Then set BX306 on the drone to record GNSS raw observation, ephemeris and event mark time. Next, fly the drone, make the base and the rover record data at the same time. After flight, download data from the base and the rover and conduct post processing using our Tersus GeoPix software.



2. Hardware Connection

2.1 Power Supply

BX306 PPK Receiver is powered by 5V~15V DC. (A power bank with 5V output or 12V power supply comes with UAV). The antenna is fed through the BX306 receiver and no external power is required.



Figure 2.1 Connect power cable to the DC port of BX306

2.2 EVENT Connection

Connect hot shoe adapter to the camera using the hot shoe cable (Figure 2.2 and 2.3), then connect the hot shoe connector to the EVENT connector of the 20pin external cable (Figure 2.4 and 2.5).



Figure 2.2 Hot shoe adapter and hot shoe cable





Figure 2.3 Connect hot shoe adapter to the camera



Figure 2.4 Outline of the 20pin external cable



Figure 2.5 Connect hot shoe connector to the EVENT connector



2.3 Connection Diagram

The connection diagram of Tersus UAV PPK Solution is as follows:



Figure 2.6 Connection diagram of Tersus UAV PPK Solution

In the above connection diagram, the AX3705 helix antenna is recommended to be installed as shown in below Figure 2.7. Ensure the AX3705 helix antenna is installed vertically and the bottom of the antenna is above the UAV. The installation requirement for AX3703 GNSS aviation antenna is the same.

Note: It is suggested to keep the antenna away from metal devices to avoid signal interference.





Figure 2.7 Recommended installation of AX3705 helix antenna on the UAV



3. Software Configuration

3.1 Base Station

The base station is installed in a high-lying, open environment and close to the area to be surveyed. The command configuration in Tersus GNSS Center is as follows:

LOG FILE RANGEB ONTIME 1	//output 1Hz observation data to the
	storage device
LOG FILE GPSEPHEMB ONTIME 30	//output 30s interval of GPS ephemeris to
	the storage device
LOG FILE GLOEPHEMERISB ONTIME 30	//output 30s interval of GLONASS
	ephemeris to the storage device
LOG FILE BDSEPHEMERISB ONTIME 30	//output 30s interval of BDS ephemeris to
	the storage device
LOG FILE BESTXYZB ONTIME 30	//output 30s interval of optimal position to
	the storage device
STORETYPE EMMC	//set the storage device as eMMC
LOGFILE AUTO	//storage mode is automatic storage
SAVECONFIG	//save the configuration

If the base station is set up at a known point, the configuration of the base station antenna coordinates can be added to fix the position of the base station. If the fix position is not configured yet, it can be input using GeoPix software which details in section 6.2.2. If there is no known point or no need of precise absolute coordinates, this step is ignored and the single point solution of base station will be used.

FIX POSITION xx.xxxxxx xxx.xxxxx xx.xxxx (latitude degree, longitude degree, MSL height meter)



Note: DO NOT directly copy the above FIX POSITION xx.xxxxx xxx.xxxxx xx.xxxxx commands, where latitude, longitude, and antenna height require entering by the customer based on the actual known point coordinates.

3.2 Rover on UAV

3.2.1 EVENT Configuration

Open Tersus GNSS Center software, type below command in the Text Console to configure BX306 receiver.

MARKCONTROL MARK1 ENABLE POSITIVE 0 800

SAVECONFIG

This command is used to control the mark inputs. Using this command, the event mark inputs can be enabled or disabled, polarity can be positive or negative, and a time offset and guard against extraneous pulses are optional.

Name		Value				
Command		MARKCONTROL signal [switch[polarity[timebias				
Command		[timeguard]]]]				
Example		MARKCONTROL MARK1 ENABLE POSITIVE 500 100				
Signal	MARK1	This command is applied to Mark1.				
0	ENABLE	Enables processing of the mark input signal (default).				
Switch	DISABLE	The mark input signal is ignored.				
Delecter	NEGATIVE	The polarity of the pulse is negative (default).				
Polarity	POSITIVE	The polarity of the pulse is positive.				
		An offset, unit is ns, to be applied to the time the mark pulse is				
TIMEDIAS		input.				
		A time period, unit is ms, during which no response to the				
TIMEGUARD		input pulses.				

Table 1 MARKCONTROL

Currently only MARK1 is supported in this PPK solution. The other commands refer to details in Log & Command document.



3.2.2 Rover Configuration

When the receiver is configured as a rover on UAV, the command configuration in Tersus GNSS Center is as follows:

LOG FILE MARKTIMEB ONMARK	/output MARK time information
LOG FILE RANGEB ONTIME 0.2	/output 5Hz observation data to the storage
(device, 0.2 means 5Hz, 0.05 means 20Hz
LOG FILE BESTXYZB ONTIME 0.2 //outp	out 5Hz optimal position to the storage device
LOG FILE GPSEPHEMB ONTIME 30	// output 30s interval of GPS ephemeris to
	the storage device
LOG FILE GLOEPHEMERISB ONTIME 30	//output 30s interval of GLONASS
	ephemeris to the storage device
LOG FILE BDSEPHEMERISB ONTIME 30	//output 30s interval of BDS ephemeris to
	the storage device
STORETYPE EMMC	//set the storage device as eMMC
LOGFILE AUTO	//storage mode is automatic storage
SAVECONFIG	//save the configuration

Note: The output frequency is setup according to the speed of the drone.



4. Data Quality Check

After completing the above hardware and software configurations, it is recommended to take the computer and the whole kit of UAV to the outdoor open environment to do the following check.

Connect the BX306 receiver to the computer using serial port, open Tersus GNSS Center software and type below commands in the text console window:

LOG GPGSV ONTIME 1	//output the satellites information including
	elevation angle and CN0 of the L1 frequency
LOG RANGEB ONTIME 1	//output the observation messages including CN0
	of L1 and L2 frequency

Check the signal strength of GPS, GLONASS, and BeiDou satellites in the 'Signal Strength' window. Check the elevation angle information in the 'Skyplot' window. Please ensure that at least FOUR satellites in each of the GPS/BeiDou/GLONASS satellite system has the CN0 value greater than 45 dB in Asia-Pacific area, at least FOUR satellites of GPS and GLONASS systems has the CN0 value greater than 45 dB in other countries and regions. Following figures show the satellites information using two kinds of antenna as examples:





Figure 4.1 Check satellites information using AX3705 antenna



Figure 4.2 Check satellites information using AX3703 antenna



5. Data Download

Connect the BX306 receiver to the computer using the mini USB cable, and the corresponding serial port will appear in the device manager of the computer (if there is no serial port, please download the USB driver for Windows system from the official website https://www.tersus-gnss.com/software /david-receiver).

Open 'TersusDownload.exe' and select the corresponding serial port. Select 'use current baudrate (USB:80KB/Second, Serial:8~32KB/S)' for the 'Download Speed' and click [START] to start.

DownLoad Port:	COM20	~
DownLoad Speed:	use current baudrate(USB:80KB/Second, Ser	al:8~3) 🗸
Progress Info:		
	Start	

Figure 5.1 Select serial port and download speed

After waiting for the software recognize the USB transmission baud rate, the software automatically pops up the file name and other information stored in the eMMC. Select the storage directory for the downloaded data in 'DownloadPath'. Refer to the figure below.



DownloadPath	E:\TersusGNSS_D	ATA\20180905	lourland		Select	View
Media	EMMC	FreeSpace	3756068	KB	SelectAll	
FileName	0 18090 306 200 7. dat 0 18090 50 1532 7. dat	UTC Time 20180903 6:20 20180905 1:53	Size 282587 66405	status		

Figure 5.2 Select download path

Select the data needs to be downloaded and click [Download] to start the download as follows:

TersusDownlo	ad					
DownloadPath	E:\TersusGNSS_D	ATA\20180905			Select	View
Auto Create I	RINEX File(\$Downloa	dPath/RINEX) after (download			
Media	EMMC	FreeSpace	3756044	KB	SelectAll	
FileName	80903062007.dat 80905015327.dat	UTC Time 20180903 6:20 20180905 1:53	Size 282587 91051	status Downloa	ading	
Defeat	Downlos	d dele	tofile	Stop	Lide	145m daws

Figure 5.3 Download data in progress

When the data download is completed, 'OK' is displayed in the 'status' of the file information window.



DownloadPath	E:\TersusGNSS	_DATA\20180905 badPath/RINEX) after (lownload		Select	View
Media	EMMC] FreeSpace	3756044	KB	SelectAll	
FileName		UTC Time	Size	status		
00065_2	0180903062007.dat	20180903 6:20	282587	OK		

Figure 5.4 Data download is completed



6. GeoPix User Guide

6.1 Introduction of GeoPix

Tersus GeoPix is a software for processing GNSS observation data collected by UAVs and ground base stations, and tagging EXIF coordinate information of EVENT moment photos.

Tersus GeoPix is part of Tersus Tool Suite. The latest version of Tersus Tool Suite can be downloaded from Tersus official website (<u>https://www.tersus-gnss.com/software</u>). Install the Tersus Tool Suite software, and GeoPix can be found under the Tersus GNSS Center in the Start menu (in Windows 10 operating system for example).



Figure 6.1 TersusGeoPix in the Start menu



6.2 Guide for GeoPix

Vorking directo	ry (Picture Dir)	*Bas	e Data			*Rover Data			14
HEM						Offsets between ca	mera center and	d phase cente	r
		n			g	FRD (CM)			
]	O MRK File			
Input Base Po no position in LAT	osition (check it when base data file) Lon	DEG ODMm(DD He	MM.mm) ODMS ght(Ellipsoid)	(DD,MM,SS) Metres	Use Event N	Nark UTC Time to repla	ice Capture Tim	e of the pictu	res
FileName	CreateTime	ModifyTime	CaptureTime		UTC TIME	Latitude	Longitude	Altitude	Po
					<				
					Map Use Go	oogle.com C	Baidu Map		
		Origina	l Latitude						
		Tagge	d Latitude						
		Origina	Longitude						
		Tagge	d Longitude						
		Origina	Altitude						
			multure						
		Tagge	d Altitude						

Open Tersus GeoPix software and get below interface.

Figure 6.2 Main interface of Tersus GeoPix

6.2.1 Set Working Directory and Import Pictures

Click [Select] on the right of 'Working directory (Auto load pictures with geotag if there are pictures in this directory)', select the folder of the pictures taken by the camera at the time of triggering EVENT as the working directory, and the software automatically recognize the pictures and display the photo shooting time and other information in the software. (Temporarily supports pictures of .JPG and .CR2 format only)



Working directory (Picture Dir) *Base Data *Rover Data Ci\Users\Miki\Desktop\UAV_DATA\Picture im Offsets between camera center and phase center PHEM Offsets between camera center and phase center Im Offsets between camera center and phase center Imput Base Postion (check it when opposition base data file) Im Im Im Im LAT Lon Height(Ellipsoid) Metres Image Create Time ModifyTime Capture Time Im Image Create Time Im doffy7111 4:00: 2018:07:31 1:4:00:35 Image Create Time Im doffy7131 1:4:00: 2018:07:31 1:4:00:35 Image Create Time Im doffy713 1:4:00: 2018:07:31 1:4:00:35 Image Create Time Image Create Time Im doffy713 1:4:00: 2018:07:31 1:4:00:35 Image Create Time Image Create Time<						
C:\Users\MMk\Desktop\UAV_DATA\Picture Offsets between camera center and phase center PHEM Offsets between camera center and phase center @ FRD (CM) Offsets between camera center and phase center @ Use Event Mark UTC Time to replace Capture Time of the pictures UTC TIME Latitude Longitude Altitude Prove Outpoints and the condonononon Tagged Latitude Not JPG/No Tag Original Latitude 0.0000000 Tagged Latitude Not JPG/No Tag Original Altitude 0.000000 Tagged Altitude Not JPG/No Tag Original Altitude 0.000000 Tagged Altitude Not JPG/No Tag	/orking directory (Picture Dir) *Base Data		*Rover Data			
Offsets between camera center and phase center Inn Inn Inc Inn Inn Inn	C:\Users\Miki\Desktop\UAV_DATA\Picture					
Image: State of the state	HEM		Offsets between ca	mera center and	l phase cente	r
Image: Construction of the construc	n.	g	FRD (CM)			
Imput Base Position (check it when o position in base data file) Imput Base Position in Position in Position in Base Position in Base Position in Position Position in Position Posite Position Position Position Position Position Positio	c		O MRK File			
MG_0132.jpg 2020/10/22 11:24: 2018/07/31 14:06: 2018:07:31 14:06:35 MG_0133.jpg 2020/10/22 11:24: 2018/07/31 14:07: 2018:07:31 14:07:03 MG_0135.jpg 2020/10/22 11:24: 2018/07/31 14:07: 2018:07:31 14:07:03 MG_0135.jpg 2020/10/22 11:24: 2018/07/31 14:07: 2018:07:31 14:07:04 MG_0135.jpg 2020/10/22 11:24: 2018/07/31 14:07: 2018:07:31 14:07:02 PICI C:\Users\Miki\Desktop\UAV_DATA\Picture_MG_0132.jpg Image: Comparison of the comparison o	LAT Lon Height(Ellipsoid) Metres FileName CreateTime ModifyTime CaptureTime	Use Event I	Aark UTC Time to repla	Longitude	e of the pictu Altitude	res Po
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M _ Mc_0136 jpg 2020/10/22 11:24: 2018/07/31 14:07: 2018:07:31 14:07:14 M _ Mc_0137 jpg 2020/10/22 11:24: 2018/07/31 14:07: 2018:07:31 14:07:23 v PIC1 C:\Users\Mik\Desktop\UAV_DATA\Picture_MG_0132.jpg Original Lattude 0.00000000 Tagged Lattude Not JPG/No Tag Original Alttude 0.0000000 Tagged Alttude Not JPG/No Tag Original Alttude Not JPG/No Tag	MG_0135.jpg 2020/10/22 11:24: 2018/07/31 14:07: 2018:07:31 14:07:06					
PIC1 C:\Users\Miki\Desktop\UAV_DATA\Picture_MG_0132.jpg Original Lattude 0.00000000 Tagged Lattude Not JPG/No Tag Original Longitude 0.00000000 Tagged Altude Not JPG/No Tag Original Altude 0.0000000 Tagged Altude Not JPG/No Tag	✓ _MG_0136.jpg 2020/10/22 11:24: 2018/07/31 14:07: 2018:07:31 14:07:14 ✓ MG_0137.jpg 2020/10/22 11:24: 2018/07/31 14:07: 2018:07:31 14:07:23					
PIC1 C:\Users\Miki\Desktop\UAV_DATA\Picture_MG_0132.jpg	<u> </u>					
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Original Altitude 0.000000 Tagged Altitude Not JPG/No Tag	Tagged Longitude Not JPG/No Tag					
Tagged Altitude Not JPG/No Tag	Original Altitude 0.000000					

Figure 6.3 Select a folder for working directory

6.2.2 Import Base Data and Rover Data

For Base Data and Rover Data, select the downloaded base data and rover data respectively, in which base data supports three kinds of formats including Tersus Binary (*.dat;*.trs), RINEX file (*.*o), and RTCM (*.dat); rover data supports Tersus Binary (*.dat;*.trs) only.

<u>!</u>	Note: Select Tersus Binary (*.dat;*.trs) when the observation data is obtained using
	Tersus GNSS receiver.

If the antenna coordinates of base station have been configured using the FIX POSITION command (details refer to section 3.1) in the base station configuration,





there is no need to check the 'Input Base Position (check it when no position in base data file)' which is shown in Figure 6.4.

If the FIX POSITION command is not configured, it is needed to check this option and input the antenna coordinates of the base station. The coordinates are input in the DEG format (shown in Figure 6.6), DMm (DDMM.mm) format, or DMS (DD, MM, SS) format.

C:\Users\Miki\Desktop\UAV_DATA\Picture C:\Users\Miki\Desktop\UAV_DATA\BASE.			C:\Users\Miki\Deskt	op\UAV_DATA\	ROVER.dat	
HEM JInput Base Position (check it when) DEG	ODMm(DDMM.mm) ODMS(DD.MM.SS)		Offsets between ca	mera center and	d phase cente	er
LAT Lon	Height(Ellipsoid) Metres	Use Event	Mark UTC Time to repla	ace Capture Tim	e of the pictu	ires
FileName Create Time Moo ✓ _MG_0132.jpg 2020/10/22 11:24: 201 ✓ _MG_0133.jpg 2020/10/22 11:24: 201 ✓ _MG_0134.jpg 2020/10/22 11:24: 201 ✓ _MG_0135.jpg 2020/10/22 11:24: 201 ✓ _MG_0135.jpg 2020/10/22 11:24: 201 ✓ _MG_0135.jpg 2020/10/22 11:24: 201	lifyTime CaptureTime 8/07/31 14:06: 2018:07:31 14:06:35 8/07/31 14:06: 2018:07:31 14:06:52 8/07/31 14:07: 2018:07:31 14:07:03 8/07/31 14:07: 2018:07:31 14:07:03 8/07/31 14:07: 2018:07:31 14:07:14 8/07/31 14:07: 2018:07:31 14:07:14 8/07/31 14:07: 2018:07:31 14:07:23	UTC TIME	Latitude	Longitude	Altitude	Po
PICI C:\Users\Mk\Desktop\UAV_DAT/	\Picture_MG_0132.jpg Original Latitude 0.00000000 Tagged Latitude Not JPG/No Tag Original Longitude 0.00000000 Tagged Longitude Not JPG/No Tag	Map Use G	oogle.com C) Baidu Map		

Figure 6.4 Select base data and rover data without base position

In the EPHEM option, you can import precise ephemeris to assist the raw observation data to calculate for more precision position. Click [..n] to open GPS ephemeris file, [..g] to open GLONASS ephemeris file, [..c] to open BDS ephemeris file, and [..l] to open Galileo ephemeris file.

In the 'Offset' option, configure the elevation offset FRD (cm) between the antenna phase center and the camera focus, which is the fixed elevation difference of the camera focus elevation minus the antenna phase center elevation.

FRD: Front, Right and Down offset (unit: cm) taking the antenna phase center as the



origin, which is shown as below.



Figure 6.5 FRD description

MRK file is the 3D attitude data in RTCM format especially for DJI drones.

Check the pictures according to the needs to determine whether to tag the picture. The quantity of the pictures needs to be the same as the quantity of the EVENTs, and the pictures are arranged in chronological order in the software to ensure alignment with the EVENTs.



C:\Users\Miki\Desktop\UAV_DATA\PCVER.dat C:\Users\Miki\Desktop\UAV_DATA\BASE.DAT C:\Users\Miki\Desktop\UAV_DATA\BASE.DAT C:\Users\Miki\Desktop\UAV_DATA\BASE.DAT C:\Users\Miki\Desktop\UAV_DATA\ROVER.dat Offsets between camera center and phase center Fiel C:\Users\Miki\Desktop\UAV_DATA\BASE.DAT C:\Users\Miki\Desktop\UAV_DATA\B	Working directory (Picture Dir)	*Base Data		*Rover Data			
HEM Offsets between camera center and phase center Ind Ind Ind Induit Base Position (check it when oposition in base data file) OEG DMm(DDMM.mm) DMS(DD,MM,SS) LAT 31.19040097 Lon 121.59319263 Height(Ellipsoid) #0.2955 Metres ModifyTime Capture Time Indiana Indiana UTC Time to replace Capture Time of the picture Image: ModifyTime Capture Time Capture Time Indiana Indiana Indiana Image: ModifyTime Capture Time Capture Time Indiana Indiana Indiana Indiana Image: ModifyTime Capture Time Capture Time Indiana Indiana Indiana Altitude Indiana Image: ModifyTime Capture Time Capture Time Indiana Indi	C:\Users\Miki\Desktop\UAV_DATA\Picture	C:\Users\Miki\Desktop\UAV_DATA\BASE.DAT		C:\Users\Miki\Deskt	p\UAV_DATA\	ROVER.dat	
n d d d d .	HEM			Offsets between ca	mera center and	d phase cente	·
Imput Base Position (check it when beging DBG DMm(DDMM.mm) DMS(DD,MM,SS) Input Base Position (check it when base data file) AT 31.19040097 Lon 121.59319263 Height(Ellipsoid) H0.2957 Metres ModifyTime CaptureTime CaptureTime M.MG.01332,jpg 2020/10/22 11:24: 2018/07/31 14:06: 2018:07:31 14:06:52 M.MG.01333,jpg 2020/10/22 11:24: 2018/07/31 14:07: 2018:07:31 14:07:06 M.MG.0135,jpg 2020/10/22 11:24: 2018/07/31 14:07: 2018:07:31 14:07:06 M.MG.0136,jpg 2020/10/22 11:24: 2018/07/31 14:07: 2018:07:31 14:07:06 M.MG.0136,jpg 2020/10/22 11:24: 2018/07/31 14:07: 2018:07:31 14:07:06 M.MG.0136,jpg 2020/10/22 11:24: 2018/07/31 14:07: 2018:07:31 14:07:06 M.MG.0137,jpg 2020/10/22 11:24: 2018/07/31 14:07: 2018:07:31 14:07:06 M.MG.0136,jpg 2020/10/22 11:24: 2018/07/31 14:07: 2018:07:31 14:07:06 M.MG.0137,jpg 2020/10/22 11:24: 2018/07/31 14:07: 2018:07:31 14:07:07:06 M.MG.0137,jpg 2020/10/22 11:24: 2018/07/31 14:07: 2018:07:31 14:07:07:06 <td></td> <td>n</td> <td>g</td> <td>FRD (CM)</td> <td></td> <td></td> <td></td>		n	g	FRD (CM)			
Input Base Position (check it when operation in base data file) DEG ODMm(DDMM.mm) ODMS(DD,MM,SS) AT 31.19040097 Lon 121.59319263 Height(Ellipsoid) 10.2957 Metres FleName Create Time ModifyTime Capture Time Image: Capture Time Imagee: Capture Tim		c]	O MRK File			
Image: Construction of the second	Mercane Deader Infle Moduly I MG_0132.jpg 2020/10/22 11:24: 2018/07 MG_0133.jpg 2020/10/22 11:24: 2018/07 MG_0134.jpg 2020/10/22 11:24: 2018/07 MG_0135.jpg 2020/10/22 11:24: 2018/07	Imme Capture imme //31 14:06: 2018:07:31 14:06:35 //31 14:06: 2018:07:31 14:06:52 //31 14:07: 2018:07:31 14:07:03 //31 14:07: 2018:07:31 14:07:06	UTC TIME	Latitude	Longitude	Aicicude	P
PICI C:\Users\Miki\Desktop\UAV_DATA\Picture_MG_0132.jpg Original Latitude 0.00000000 Tagged Latitude 0.00000000 Original Longitude 0.00000000	☐ _MG_0135.jpg 2020/10/22 11:24: 2018/0 ☐ _MG_0136.jpg 2020/10/22 11:24: 2018/0	//31 14:07: 2018:07:31 14:07:06 //31 14:07: 2018:07:31 14:07:14 //31 14:07: 2018:07:31 14:07:23					
Tagged Longitude Not JPG/No Tag	⊴_MG_0137.jpg 2020/10/22 11:24: 2018/07						

Figure 6.6 Select base data and rover data with base position

6.2.3 Data Processing

Click the 'RUN' at the bottom to start GNSS post-processing as shown below.

Warking directory (Distance Di-)		-		**			
working airectory (Picture Dir)	*Base	Data		*Rover Data		ULAV DATA	RO
ts\2 GNSS Kits\PPK\test\UAV_DATA\F	D:\A_	_projects\2 GNSS Kits\PPK\test\	UAV_DATA(BA:	D:\A_projects\2 G	INSS KITS\PPK\Test	UAV_DATA	
PHEM				Offsets between o	camera center and	phase center	r
			9	FRD (CM)			
	c			O MRK File			
FleName Create Time ✓ M6_0132.jpg 2018/09/06 1 ✓ M6_0133.jpg 2018/09/06 1 ✓ M6_0134.jpg 2018/09/06 1 ✓ M6_0135.jpg 2018/09/06 1 ✓ M6_0135.jpg 2018/09/06 1 ✓ M6_0135.jpg 2018/09/06 1 ✓ M6_0135.jpg 2018/09/06 1 ✓ M6_0137.jpg 2018/09/06 1	Please wait until this p Progress Info Begin PPK	process finish!!!				Altitude	Po
PIC1 D:\A_projects\2 GN					Jse Google.cn	🔿 Baidu	Мар
	Original L Tagged U Original L Tagged U Original A Tagged J	Latitude 0.00000000 Latitude Not JPG/No Tag Longitude 0.00000000 Longitude Not JPG/No Tag Altitude 0.000000 Altitude Not JPG/No Tag					

Figure 6.7 Click RUN to start data processing



If the captured pictures do not contain EXIF information, the software automatically tag the pictures according to the calculated antenna coordinates at the EVENT time (add the EXIF information to the pictures). Or manually tag the pictures by clicking the 'Geotag' at the bottom of the above figure. The geotagged result list is shown as below.

FileName	Latitude	Longitude	Altitude	CantureTime	Pos ^
MC 0122 in a	NO1 10001 CO1		16.040	2010:07:21 1	FUS
_MG_0132.jpg	N31.19821691	E121.60010/34	16.049	2018:07:31 1	FIX
_MG_0133.jpg	N31.19809810	E121.59984354	16.214	2018:07:31 1	FIX
_MG_0134.jpg	N31.19936242	E121.59954359	10./92	2018:07:31 1	FIX
_MG_0135.jpg	N31.1995/368	E121.59944/15	17.104	2018:07:31 1	FIX
_MG_0136.jpg	N31.1999/256	E121.59928040	16.121	2018:07:31 1	FIX
_MG_0137.jpg	N31.20020036	E121.59919953	16.118	2018:07:31 1	FIX
_MG_0138.jpg	N31.20029112	E121.59961428	16.242	2018:07:31 1	FIX
_MG_0139.jpg	N31.20031342	E121.6005901/	17.413	2018:07:31 1	FIX
_MG_0140.jpg	N31.20031590	E121.60222550	17.494	2018:07:31 1	FIX
_MG_0141.jpg	N31.20031857	E121.60313210	16.393	2018:07:31 1	FIX
_MG_0142.jpg	N31.20031813	E121.60396121	16.282	2018:07:31 1	FIX
_MG_0143.jpg	N31.20032386	E121.60535617	16.426	2018:07:31 1	FIX
_MG_0144.jpg	N31.20032370	E121.60654664	16.304	2018:07:31 1	FIX
_MG_0145.jpg	N31.20032450	E121.60725312	16.166	2018:07:31 1	FIX
_MG_0146.jpg	N31.20032433	E121.60737379	16.201	2018:07:31 1	FIX
_MG_0147.jpg	N31.20035730	E121.60795783	16.393	2018:07:31 1	FIX
_MG_0148.jpg	N31.20067506	E121.60825659	16.197	2018:07:31 1	FIX 🗸
<					>

Figure 6.8 Geotagged Result List

TersusGeoPix	×
Finished! You can check the GeoTagg .\\geotag	ed pictures and ppk.txt in
	ОК

Figure 6.9 Geotag finished



6.2.4 View processed results

After the geotag for the pictures is completed, the software automatically generates folders named 'geotag' and 'workingtemp' in the working directory, where the 'geotag' folder contains the pictures that have been tagged and ppk.txt file which indicates the information of the tagged pictures, and the 'workingtemp' folder contains the post-processing positioning results and the RINEX format file.

The coordinate information of the tagged pictures including latitude, longitude, altitude and position status can be seen by clicking the picture file name in Tersus GeoPix software. Whether the position status of the tagged picture is FIX or Float can also be seen in the ppk.txt file which locates in 'geotag' folder.

orking directory (Picture Dir)	*Base Data		*Rover Data			
:\Users\Miki\Desktop\UAV_DATA\Picture	C:\Users\Miki\Desktop\UAV_DATA\BASE.E	DAT	C:\Users\Miki\Deskto	p\UAV_DATA\RC	VER.dat	
IEM			Offsets between can	nera center and p	hase cente	r
	n	g	FRD (CM)			
	c		O MRK File			
ileName CreateTime ModifyT	ime Capture Time		Latitude	Longitude	Altitude	P
MG_0132.jpg 2020/10/22 11:24: 2018/0	7/31 14:06: 2018:07:31 14:06:35	2018:07:3	1 06:2 N31 11 5	E121 36 0	16.0490	F
_MG_0133.jpg 2020/10/22 11:24: 2018/0	7/31 14:06: 2018:07:31 14:06:52	2018:07:3	1 06:2 N31 11 5	E121 35 5	16.2142	F
_MG_0134.jpg 2020/10/22 11:24: 2018/0	7/31 14:07: 2018:07:31 14:07:03	2018:07:3	1 06:2 N31 11 5	E121 35 5	16.7928	F
MG_0135.jpg 2020/10/22 11:24: 2018/0	7/31 14:07: 2018:07:31 14:07:06	2018:07:3	1 06:2 N31 11 5	E121 35 5	17.1642	F
✓ _MG_0136.jpg 2020/10/22 11:24: 2018/03	7/31 14:07: 2018:07:31 14:07:14	2018:07:3	1 06:2 N31 11 5	E121 35 5	16.1210	F
	//31 14.0/ 2018.0/.31 14.0/.23	<				>
IC3 C:\Users\Miki\Desktop\UAV_DATA\Pic	ture_MG_0134.jpg	Map Use Go	ogle.com OI	Baidu Map		
		ARAGE	小时自助银行			S. 1
	Original Latitude 0.00000000	Contraction (198)		🗧 Gaoke Mi	iddle Rd	123
	Taggod Latitudo N31 10036242	CARACTER O	E	a lanca		
1/1	Tagged Latitude NS1.19930242	2010		The same and		10.
	Original Longitude 0.00000000	e e		and the same of		
and the second se	Tagged Longitude E121.59954359				A MINO	134
E. S.	Original Altitude 0.000000	R	H. S. Sandarda			
		Carl Ko	States of the second	CORE (MILLION)	A DECK	and the second second
	Tagged Altitude 16.792801	COLUMN	A CONTRACTOR OF	and the Mar	A DECEMBER OF	F

Figure 6.10 Check the coordinate information of the tagged pictures

Click ViewPPK at the bottom right of the main interface to view the ppk results in text file as below.



ppk.txt - Notepad						<u></u>		×
<u>File Edit Format View H</u> elp	2				12 12 11			
#name	Latitude Longitude	e Height LatStd	LonStd	HStd	status			^
_MG_0132.jpg	31.19821691109	121.60010734381	16.0490	0.0120	0.0160	0.0310	FIX	
_MG_0133.jpg	31.19869816079	121.59984354162	16.2142	0.0110	0.0139	0.0268	FIX	
_MG_0134.jpg	31.19936242022	121.59954358503	16.7928	0.0160	0.0285	0.0407	FIX	
_MG_0135.jpg	31.19957367987	121.59944714697	17.1642	0.0092	0.0094	0.0212	FIX	
_MG_0136.jpg	31.19997255719	121.59928040063	16.1210	0.0080	0.0079	0.0196	FIX	
_MG_0137.jpg	31.20020036247	121.59919952804	16.1187	0.0070	0.0062	0.0162	FIX	
_MG_0138.jpg	31.20029112287	121.59961427616	16.2427	0.0090	0.0060	0.0179	FIX	
_MG_0139.jpg	31.20031341969	121.60059017200	17.4138	0.0131	0.0100	0.0250	FIX	
_MG_0140.jpg	31.20031589563	121.60222550119	17.4944	0.0121	0.0096	0.0227	FIX	
MG_0141.jpg	31.20031856639	121.60313210279	16.3931	0.0090	0.0080	0.0160	FIX	
MG_0142.jpg	31.20031812730	121.60396120616	16.2824	0.0106	0.0095	0.0210	FIX	
MG_0143.jpg	31.20032386010	121.60535616777	16.4264	0.0090	0.0073	0.0163	FIX	
MG 0144.jpg	31.20032369646	121.60654664461	16.3047	0.0100	0.0080	0.0190	FIX	
MG 0145.jpg	31.20032450226	121.60725311798	16.1661	0.0080	0.0070	0.0180	FIX	
MG 0146.jpg	31.20032433182	121.60737379098	16.2011	0.0081	0.0081	0.0171	FIX	
MG 0147.jpg	31,20035730386	121.60795782767	16.3939	0.0090	0.0070	0.0160	FIX	
MG 0148.ipg	31,20067506065	121.60825659110	16,1979	0.0111	0.0111	0.0231	FIX	
MG 0149.jpg	31.20094720621	121.60842126108	16.0436	0.0212	0.0448	0.0798	FIX	
_MG_0150.jpg	31.20148657672	121.60875446170	16.0765	0.0119	0.0101	0.0188	FIX	

Figure 6.11 Information in ppk.txt file

Click [ViewPlot] at the bottom to view the positioning results of the GNSS post-processing data and the location information of the EVENT moments. The example is shown in Figure 6.12 and Figure 6.13. In the screenshots below, the position status of green points are fixed, while the position status of yellow points are float.







Figure 6.12 Positioning results of the GNSS post-processing



Figure 6.13 The location information of the EVENT moments





7. Terminology

BDS	BeiDou Navigation Satellite System
DC	Direct Current
eMMC	Embedded Multi Media Card
EXIF	Exchangeable Image File Format
GLONASS	GLObal NAvigation Satellite System
GNSS	Global Navigation Satellite System
GPS	Global Positioning System
PC	Personal Computer
РРК	Post-Processing Kinematic
PPS	Pulse Per Second
RINEX	Receiver Independent Exchange format
RMS	Root Mean Squares
RTK	Real-Time Kinematic
RTCM	Radio Technical Commission for Maritime Services
UAV	Unmanned Aerial Vehicle, drone
USB	Universal Serial BUS



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