

User Manual

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User Manual For UAV PPK Solution

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Sales & Technical Support:

sales@tersus-gnss.com & support@tersus-gnss.com

More details, please visit www.tersus-gnss.com

Table of Content

Revision History.....	3
1. Introduction.....	4
2. Hardware Connection.....	5
2.1 Power Supply.....	5
2.2 EVENT Connection.....	5
2.3 Connection Diagram.....	7
3. Software Configuration.....	9
3.1 Base Station.....	9
3.2 Rover on UAV.....	10
3.2.1 EVENT Configuration.....	10
3.2.2 Rover Configuration.....	11
4. Data Quality Check.....	12
5. Data Download.....	14
6. GeoPix User Guide.....	17
6.1 Introduction of GeoPix.....	17
6.2 Guide for GeoPix.....	18
6.2.1 Set Working Directory and Import Pictures.....	18
6.2.2 Import Base Data and Rover Data.....	19
6.2.3 Data Processing.....	22
6.2.4 View processed results.....	23
7. Terminology.....	26

List of Tables

Table 1 MARKCONTROL.....	10
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List of Figures

Figure 2.1 Connect power cable to the DC port of BX306.....	5
Figure 2.2 Hot shoe adapter and hot shoe cable.....	5
Figure 2.3 Connect hot shoe adapter to the camera.....	6
Figure 2.4 Outline of the 20-pin cable.....	6
Figure 2.5 Connect hot shoe connector to the EVENT connector.....	6
Figure 2.6 Connection diagram of Tersus UAV PPK Solution.....	7
Figure 2.7 Recommended installation of AX3705 helix antenna on the UAV.....	8
Figure 4.1 Check satellites information using AX3705 antenna.....	13
Figure 4.2 Check satellites information using AX3703 antenna.....	13
Figure 5.1 Select serial port and download speed.....	14
Figure 5.2 Select download path.....	15
Figure 5.3 Download data in progress.....	15
Figure 5.4 Data download is completed.....	16
Figure 6.1 TersusGeoPix in the Start menu.....	17
Figure 6.2 Main interface of Tersus GeoPix.....	18
Figure 6.3 Select a folder for working directory.....	19
Figure 6.4 Select base data and rover data without base position.....	20
Figure 6.5 Select base data and rover data with base position.....	21
Figure 6.6 Configure RTK option.....	21
Figure 6.7 Click RUN to start data processing.....	22
Figure 6.8 Geotagged Result List.....	23
Figure 6.9 Check the coordinate information of the tagged pictures.....	24
Figure 6.10 Information in ppk.txt file.....	24
Figure 6.11 Positioning results of the GNSS post-processing.....	25
Figure 6.12 The location information of the EVENT moments.....	25

Revision History

Version	Revision Date	Change summary
1.0	20180928	Initial Release
1.1	20181108	Add position status in processed result
1.2	20190617	Change BX316R to BX306, add RTK option in section 6.2.2
1.3	20200513	Minor updates; change 40pin external cable to 20pin external cable

1. Introduction

Tersus UAV PPK solution includes BX306 PPK Receiver, AX3705 Helix Antenna or AX3703 GNSS Aviation Antenna and Tersus GeoPix Software. BX306 PPK Receiver supports multi-constellations and dual-frequencies. It has in-built 4GB memory (eMMC) for GNSS observation data recording. Very small and light AX3705 Helix Antenna and AX3703 GNSS Aviation Antenna are designed for UAV applications.

Tersus GeoPix integrates the functions of GNSS observation post processing, Event Mark interpolation and geotagging in EXIF. By clicking one button after inputting all necessary data, the software generates the result which can be used as direct input for image processing software. Tersus GeoPix is part of Tersus Tool Suite which can be downloaded from the official website: <https://www.tersus-gnss.com/software>.

The general process of this solution is as follows:

First, mount AX3705 helix antenna or AX3703 GNSS aviation antenna and BX306 PPK board on the drone, connect camera hot shoe to Event Mark port of BX306 for camera shutter synchronization. Then set BX306 on the drone to record GNSS raw observation, ephemeris and event mark time. Next, fly the drone, make the base and the rover record data at the same time. After flight, download data from the base and the rover and conduct post processing using our Tersus GeoPix software.

2. Hardware Connection

2.1 Power Supply

BX306 PPK Receiver is powered by 5V~15V DC. (A power bank with 5V output or 12V power supply comes with UAV). The antenna is fed through the BX306 receiver and no external power is required.

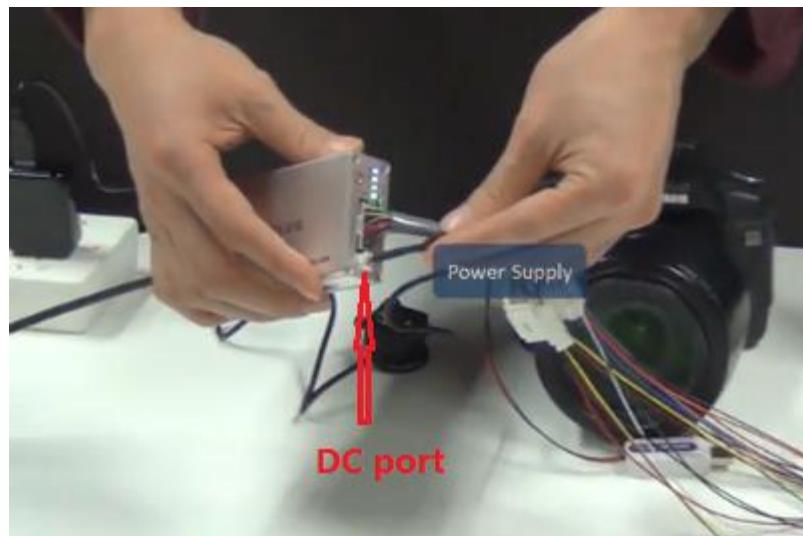


Figure 2.1 Connect power cable to the DC port of BX306

2.2 EVENT Connection

Connect hot shoe adapter to the camera using the hot shoe cable (Figure 2.2 and 2.3), then connect the hot shoe connector to the EVENT connector of the 20pin external cable (Figure 2.4 and 2.5).



Figure 2.2 Hot shoe adapter and hot shoe cable



Figure 2.3 Connect hot shoe adapter to the camera

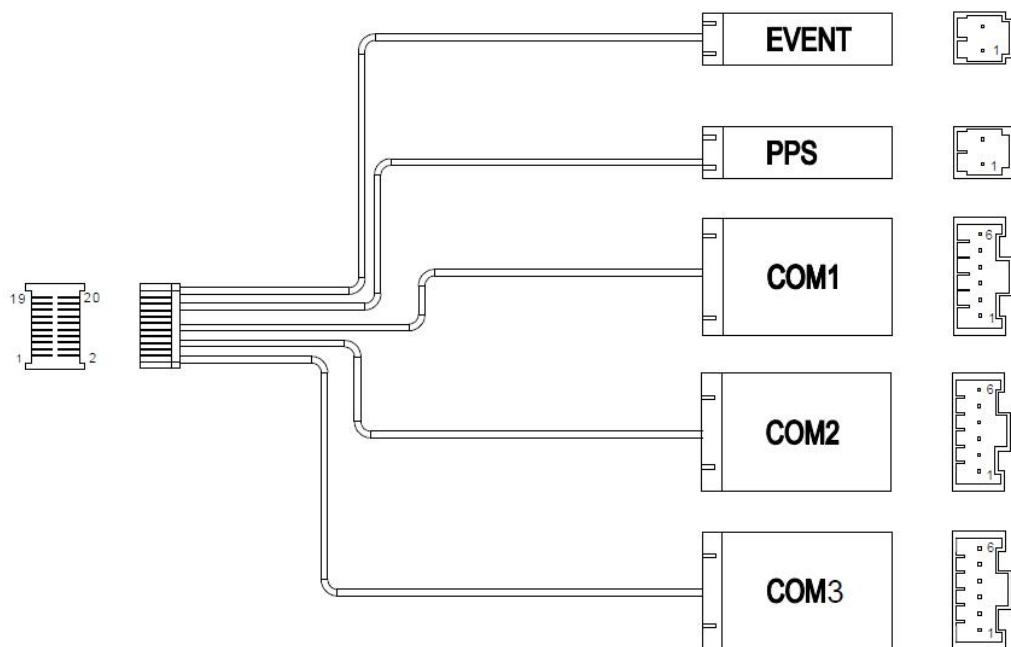


Figure 2.4 Outline of the 20pin external cable

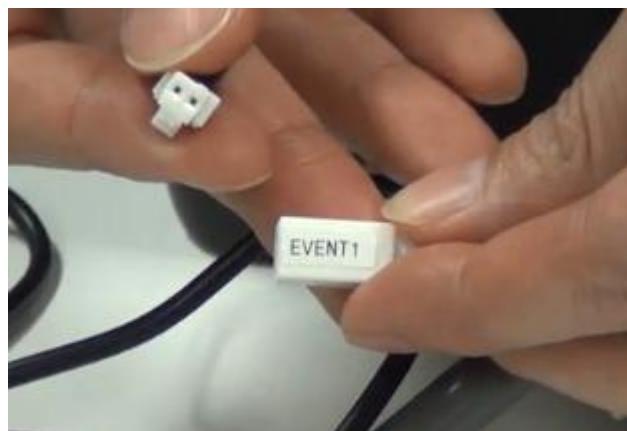


Figure 2.5 Connect hot shoe connector to the EVENT connector

2.3 Connection Diagram

The connection diagram of Tersus UAV PPK Solution is as follows:

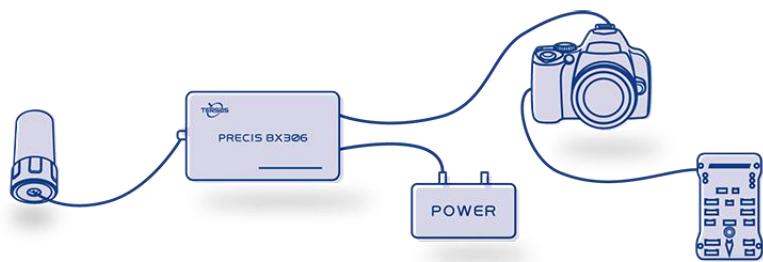


Figure 2.6 Connection diagram of Tersus UAV PPK Solution

In the above connection diagram, the AX3705 helix antenna is recommended to be installed as shown in below Figure 2.7. Ensure the AX3705 helix antenna is installed vertically and the bottom of the antenna is above the UAV. The installation requirement for AX3703 GNSS aviation antenna is the same.

Note: It is suggested to keep the antenna away from metal devices to avoid signal interference.



Figure 2.7 Recommended installation of AX3705 helix antenna on the UAV

3. Software Configuration

3.1 Base Station

The base station is installed in a high-lying, open environment and close to the area to be surveyed. The command configuration in Tersus GNSS Center is as follows:

LOG FILE RANGEB ONTIME 1	//output 1Hz observation data to the storage device
LOG FILE GPSEPHEMB ONTIME 30	//output 30s interval of GPS ephemeris to the storage device
LOG FILE GLOEPHEMERISB ONTIME 30	//output 30s interval of GLONASS ephemeris to the storage device
LOG FILE BDSEPHEMERISB ONTIME 30	//output 30s interval of BDS ephemeris to the storage device
LOG FILE BESTXYZB ONTIME 30	//output 30s interval of optimal position to the storage device
STORETYPE EMMC	//set the storage device as eMMC
LOGFILE AUTO	//storage mode is automatic storage
SAVECONFIG	//save the configuration

If the base station is set up at a known point, the configuration of the base station antenna coordinates can be added to fix the position of the base station. If the fix position is not configured yet, it can be input using GeoPix software which details in section 6.2.2. If there is no known point or no need of precise absolute coordinates, this step is ignored and the single point solution of base station will be used.

FIX POSITION xx.xxxxxx xxx.xxxxxx xx.xxxx (latitude degree, longitude degree, MSL height meter)

Note: DO NOT directly copy the above FIX POSITION xx.xxxxxx xxx.xxxxxx xx.xxxx commands, where latitude, longitude, and antenna height require entering by the customer based on the actual known point coordinates.

3.2 Rover on UAV

3.2.1 EVENT Configuration

Open Tersus GNSS Center software, type below command in the Text Console to configure BX306 receiver.

MARKCONTROL MARK1 ENABLE POSITIVE 0 800

SAVECONFIG

This command is used to control the mark inputs. Using this command, the event mark inputs can be enabled or disabled, polarity can be positive or negative, and a time offset and guard against extraneous pulses are optional.

Table 1 MARKCONTROL

Name		Value
Command		MARKCONTROL signal [switch[polarity[timebias [timeguard]]]]
Example		MARKCONTROL MARK1 ENABLE POSITIVE 500 100
Signal	MARK1	This command is applied to Mark1.
Switch	ENABLE	Enables processing of the mark input signal (default).
	DISABLE	The mark input signal is ignored.
Polarity	NEGATIVE	The polarity of the pulse is negative (default).
	POSITIVE	The polarity of the pulse is positive.
TIMEBIAS		An offset, unit is ns, to be applied to the time the mark pulse is input.
TIMEGUARD		A time period, unit is ms, during which no response to the input pulses.

Currently only MARK1 is supported in this PPK solution. The other commands refer to details in Log & Command document.

3.2.2 Rover Configuration

When the receiver is configured as a rover on UAV, the command configuration in Tersus GNSS Center is as follows:

LOG FILE MARKTIMEB ONMARK	//output MARK time information
LOG FILE RANGEB ONTIME 0.2	//output 5Hz observation data to the storage device, 0.2 means 5Hz, 0.05 means 20Hz
LOG FILE BESTXYZB ONTIME 0.2	//output 5Hz optimal position to the storage device
LOG FILE GPSEPHEMB ONTIME 30	// output 30s interval of GPS ephemeris to the storage device
LOG FILE GLOEPHEMERISB ONTIME 30	//output 30s interval of GLONASS ephemeris to the storage device
LOG FILE BDSEPHEMERISB ONTIME 30	//output 30s interval of BDS ephemeris to the storage device
STORETYPE EMMC	//set the storage device as eMMC
LOGFILE AUTO	//storage mode is automatic storage
SAVECONFIG	//save the configuration

Note: The output frequency is setup according to the speed of the drone.

4. Data Quality Check

After completing the above hardware and software configurations, it is recommended to take the computer and the whole kit of UAV to the outdoor open environment to do the following check.

Connect the BX306 receiver to the computer using serial port, open Tersus GNSS Center software and type below commands in the text console window:

LOG GPGSV ONTIME 1	//output the satellites information including elevation angle and CN0 of the L1 frequency
LOG RANGEB ONTIME 1	//output the observation messages including CN0 of L1 and L2 frequency

Check the signal strength of GPS, GLONASS, and BeiDou satellites in the ‘Signal Strength’ window. Check the elevation angle information in the ‘Skyplot’ window. Please ensure that at least FOUR satellites in each of the GPS/BeiDou/GLONASS satellite system has the CN0 value greater than 45 dB in Asia-Pacific area, at least FOUR satellites of GPS and GLONASS systems has the CN0 value greater than 45 dB in other countries and regions. Following figures show the satellites information using two kinds of antenna as examples:

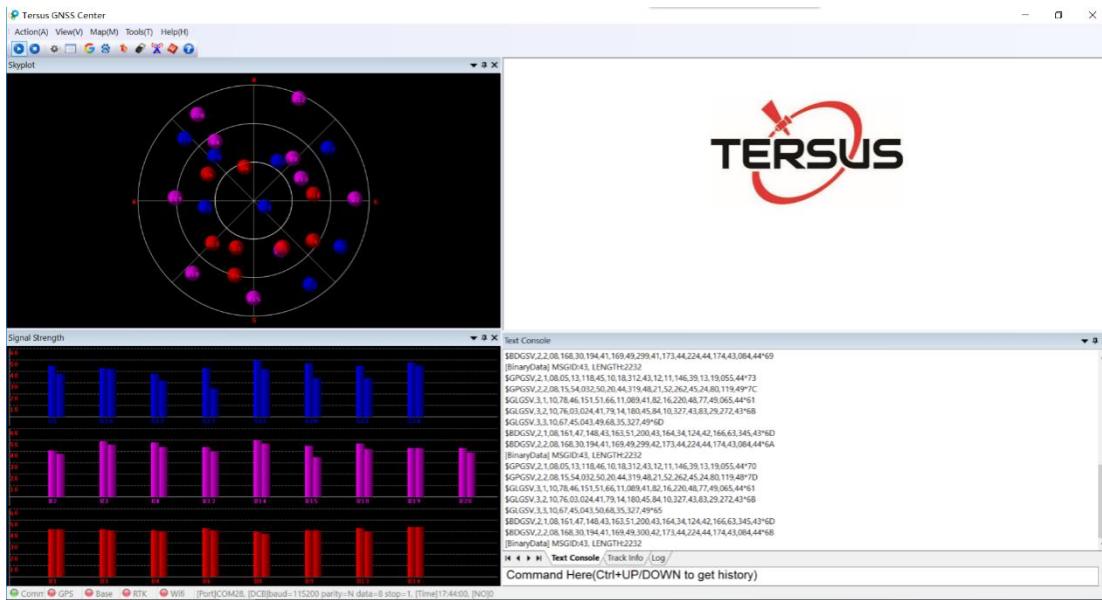


Figure 4.1 Check satellites information using AX3705 antenna

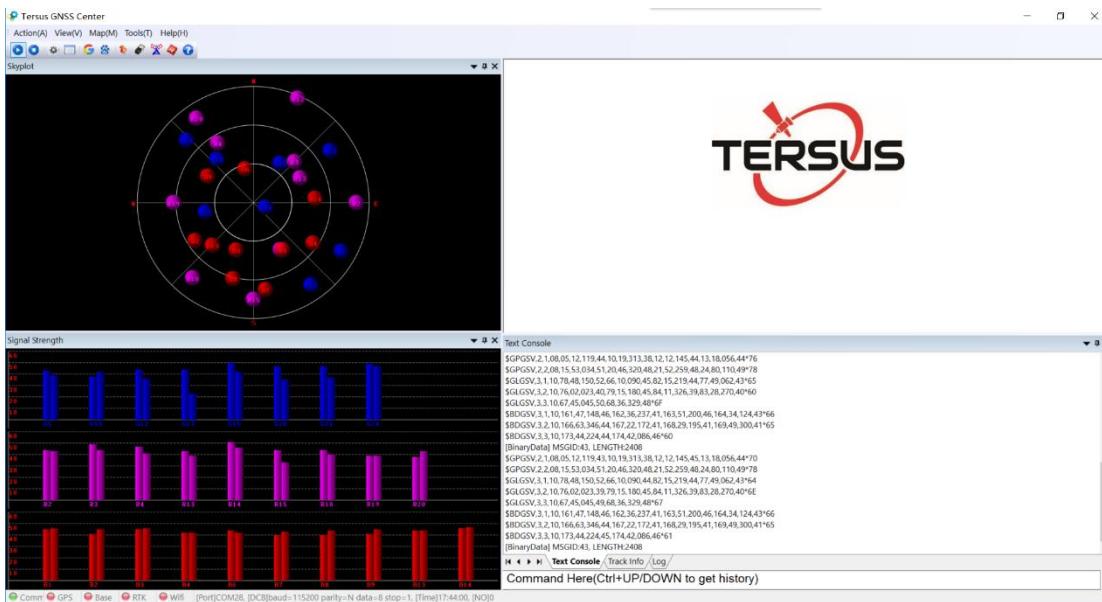


Figure 4.2 Check satellites information using AX3703 antenna

5. Data Download

Connect the BX306 receiver to the computer using the mini USB cable, and the corresponding serial port will appear in the device manager of the computer (if there is no serial port, please download the USB driver for Windows system from the official website <https://www.tersus-gnss.com/software/david-receiver>).

Open 'TersusDownload.exe' and select the corresponding serial port. Select 'use current baudrate (USB:80KB/Second, Serial:8~32KB/S)' for the 'Download Speed' and click [START] to start.

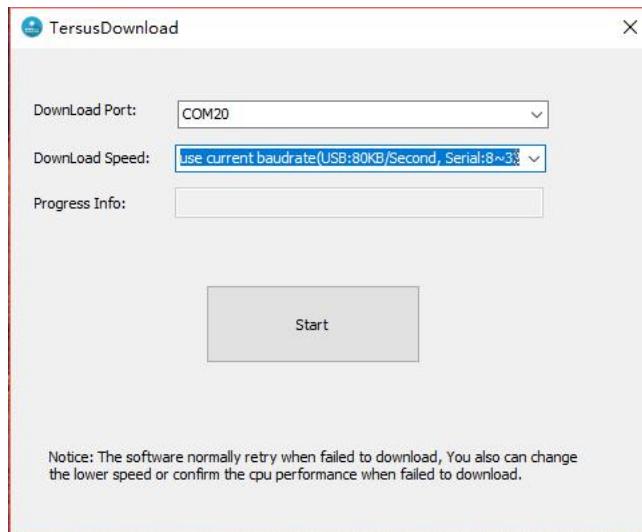


Figure 5.1 Select serial port and download speed

After waiting for the software recognize the USB transmission baud rate, the software automatically pops up the file name and other information stored in the eMMC. Select the storage directory for the downloaded data in 'DownloadPath'. Refer to the figure below.

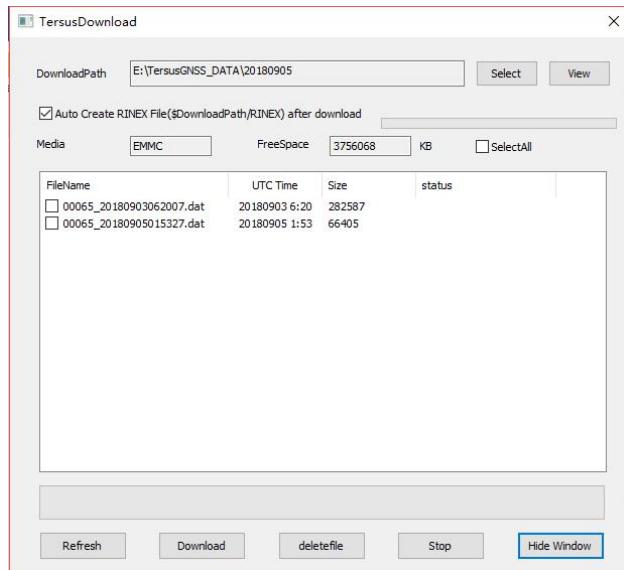


Figure 5.2 Select download path

Select the data needs to be downloaded and click [Download] to start the download as follows:

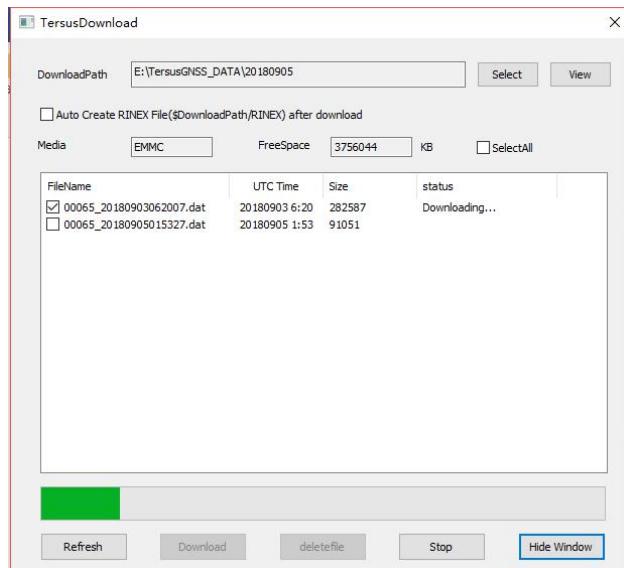


Figure 5.3 Download data in progress

When the data download is completed, 'OK' is displayed in the 'status' of the file information window.

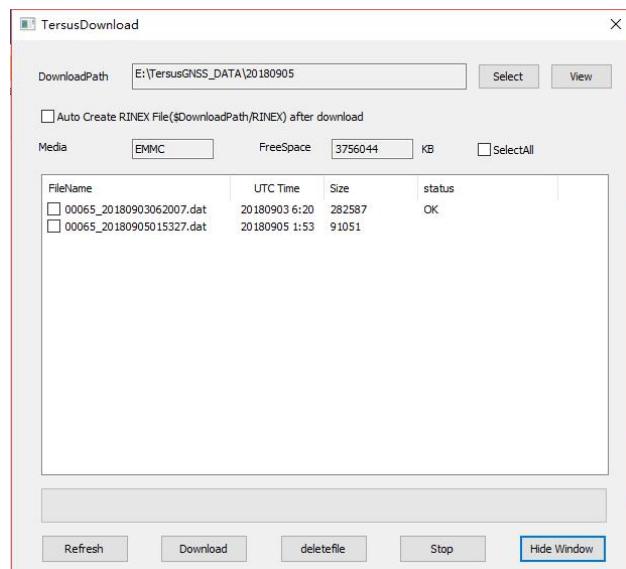


Figure 5.4 Data download is completed

6. GeoPix User Guide

6.1 Introduction of GeoPix

Tersus GeoPix is a software for processing GNSS observation data collected by UAVs and ground base stations, and tagging EXIF coordinate information of EVENT moment photos.

Tersus GeoPix is part of Tersus Tool Suite. The latest version of Tersus Tool Suite can be downloaded from Tersus official website (<https://www.tersus-gnss.com/software>). Install the Tersus Tool Suite software, and GeoPix can be found under the Tersus GNSS Center in the Start menu (in Windows 10 operating system for example).

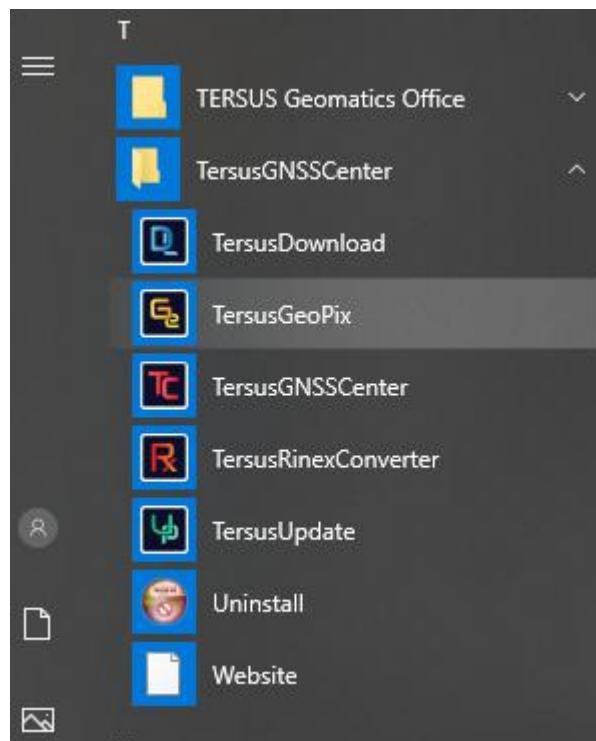


Figure 6.1 TersusGeoPix in the Start menu

6.2 Guide for GeoPix

Open Tersus GeoPix software and get below interface.

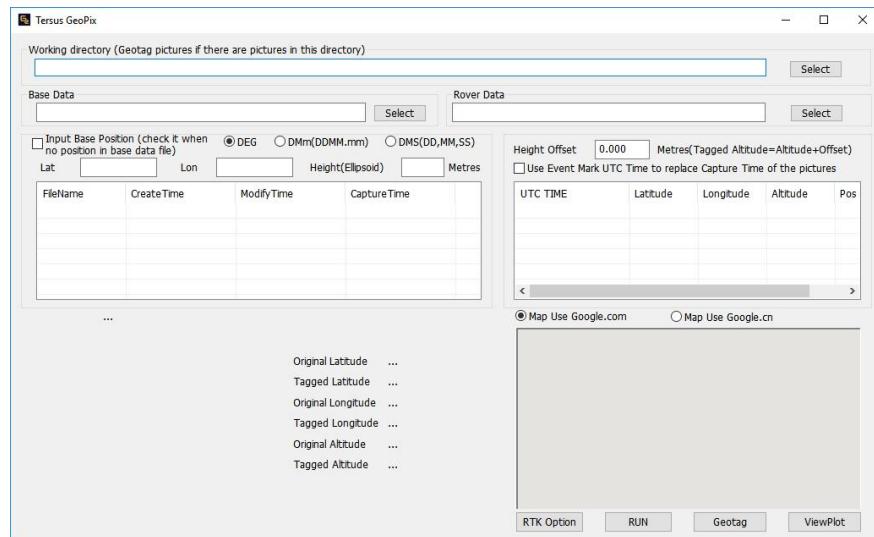


Figure 6.2 Main interface of Tersus GeoPix

6.2.1 Set Working Directory and Import Pictures

Click [Select] on the right of ‘Working directory (Auto load pictures with geotag if there are pictures in this directory)’, select the folder of the pictures taken by the camera at the time of triggering EVENT as the working directory, and the software automatically recognize the pictures and display the photo shooting time and other information in the software. (Temporarily supports pictures of .JPG and .CR2 format only)

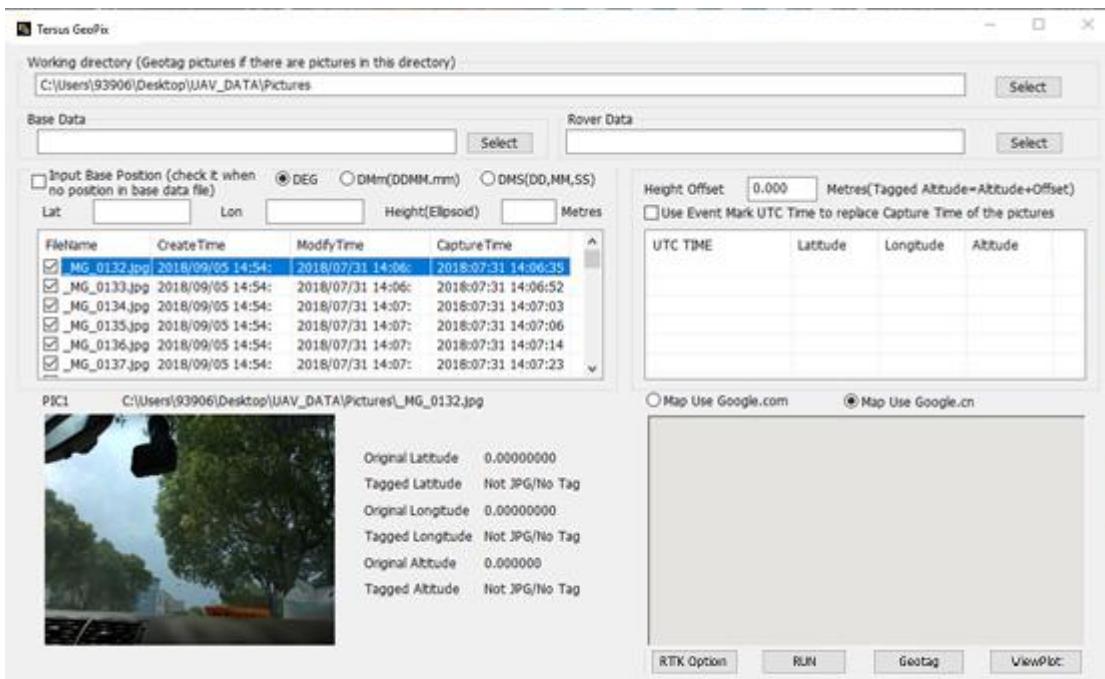


Figure 6.3 Select a folder for working directory

!	Note: If there are no pictures at the EVENT moment need to be tagged, only the appropriate folder needs to be selected as the working directory to output the PPK calculation result.
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6.2.2 Import Base Data and Rover Data

For Base Data and Rover Data, select the downloaded base data and rover data respectively, in which base data supports three kinds of formats including Tersus Binary (*.dat;*.trs), RINEX file (*.*o), and RTCM (*.dat); rover data supports Tersus Binary (*.dat;*.trs) only.

!	Note: Select Tersus Binary (*.dat;*.trs) when the observation data is obtained using Tersus GNSS receiver.
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If the antenna coordinates of base station have been configured using the FIX POSITION command (details refer to section 3.1) in the base station configuration,

there is no need to check the 'Input Base Position (check it when no position in base data file)' which is shown in Figure 6.4.

If the FIX POSITION command is not configured, it is needed to check this option and input the antenna coordinates of the base station. The coordinates are input in the DEG format (shown in Figure 6.5), DMm (DDMM.mm) format, or DMS (DD, MM, SS) format.

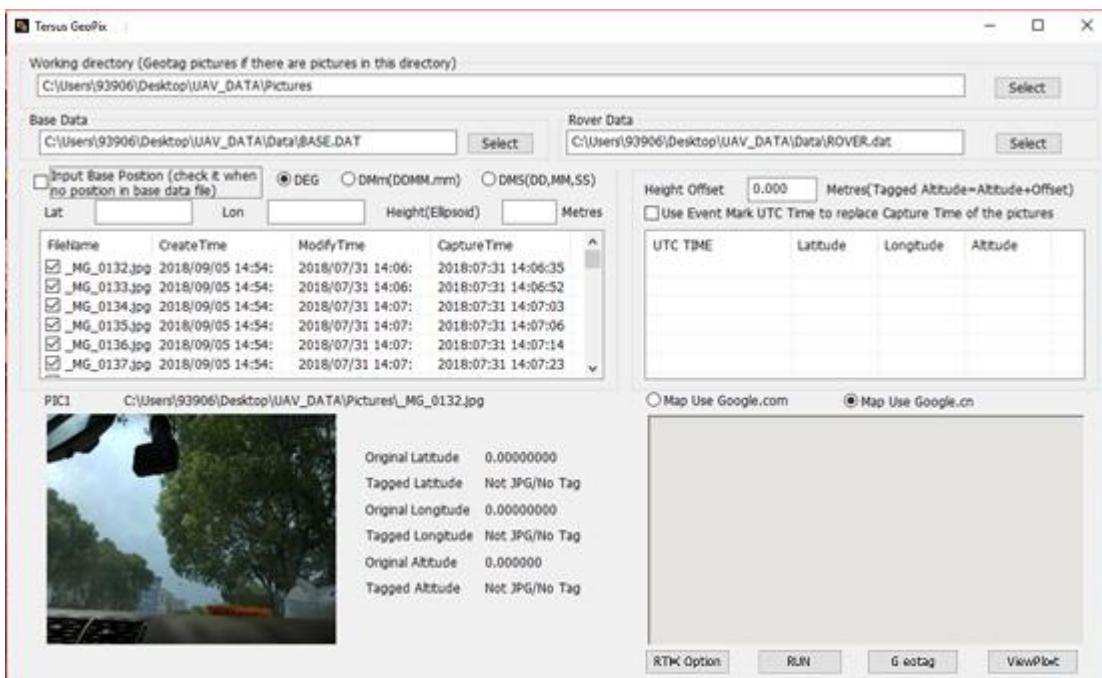


Figure 6.4 Select base data and rover data without base position

In the 'Height Offset' option, configure the elevation deviation between the antenna phase center and the camera focus, which is the fixed elevation difference of the camera focus elevation minus the antenna phase center elevation.

Check the pictures according to the needs to determine whether to tag the picture. The quantity of the pictures needs to be the same as the quantity of the EVENTS, and the pictures are arranged in chronological order in the software to ensure alignment with the EVENTS.

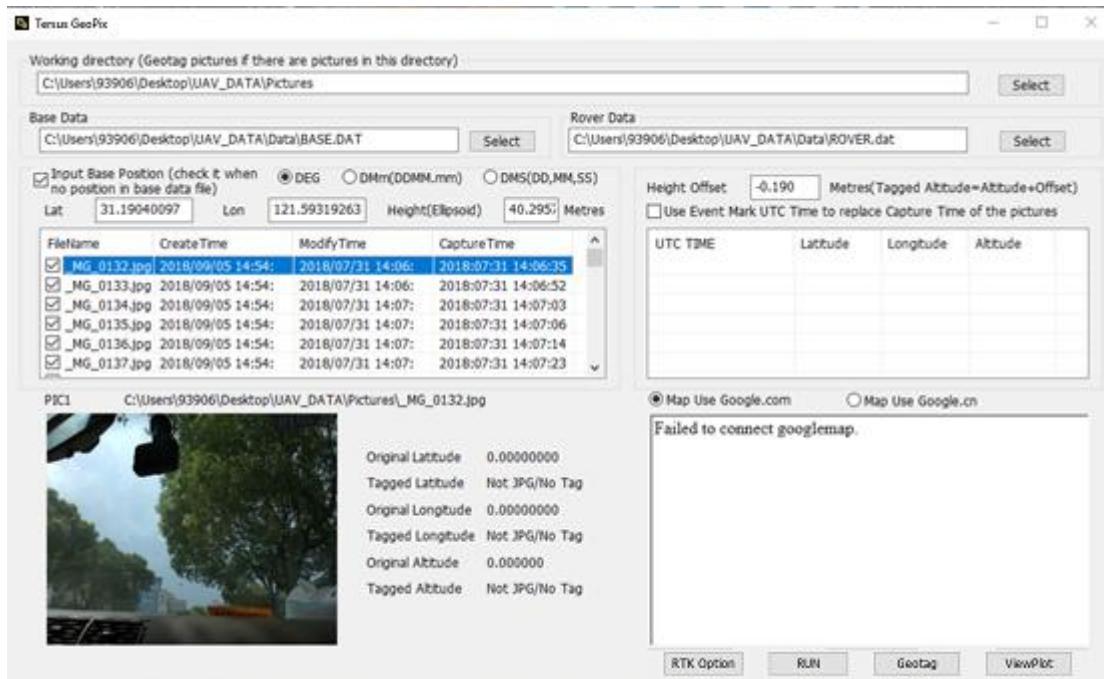


Figure 6.5 Select base data and rover data with base position

Click [RTK Option] to configure the RTK option including satellite system, frequency used to process data and the strategy of integer ambiguity resolution for different systems. The default configuration is using all three systems.

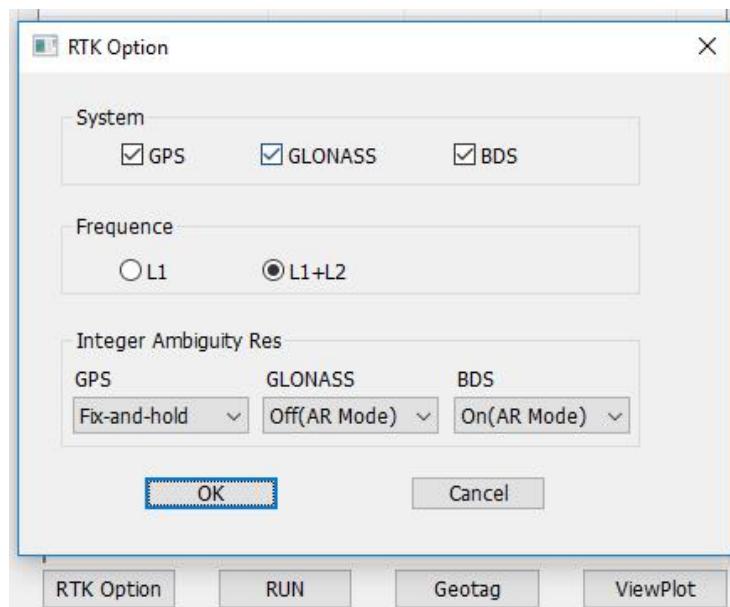


Figure 6.6 Configure RTK option

6.2.3 Data Processing

Click the 'RUN' at the bottom to start GNSS post-processing as shown in Figure 6.6 below.

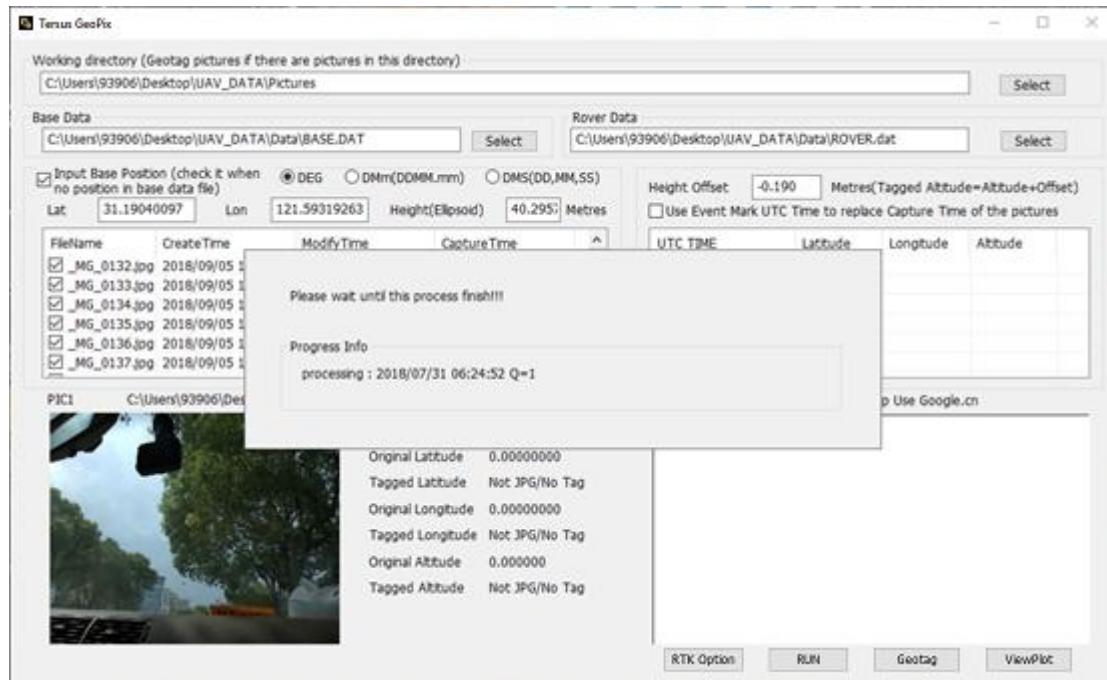


Figure 6.7 Click RUN to start data processing

If the captured pictures do not contain EXIF information, the software automatically tag the pictures according to the calculated antenna coordinates at the EVENT time (add the EXIF information to the pictures). Or manually tag the pictures by clicking the 'Geotag' at the bottom of Figure 6.6. The geotagged result list is shown as below.

Geotagged Result List

Output Dir
C:\Users\93906\Desktop\2018-7-31\JPG\geotag

FileName	Lat	Lon	Altitude	CaptureTime	Type
_MG_0132.jpg	N31.19821689	E121.60010726	16.053	2018:07:31 1...	FIX
_MG_0133.jpg	N31.19869818	E121.59984354	16.205	2018:07:31 1...	FIX
_MG_0134.jpg	N31.19936298	E121.59954526	16.747	2018:07:31 1...	FIX
_MG_0135.jpg	N31.19957363	E121.59944721	17.151	2018:07:31 1...	FIX
_MG_0136.jpg	N31.19997257	E121.59928047	16.150	2018:07:31 1...	FIX
_MG_0137.jpg	N31.20020024	E121.59919950	16.117	2018:07:31 1...	FIX
_MG_0138.jpg	N31.20029101	E121.59961426	16.240	2018:07:31 1...	FIX
_MG_0139.jpg	N31.20031336	E121.60059020	17.413	2018:07:31 1...	FIX
_MG_0140.jpg	N31.20031583	E121.60222546	17.489	2018:07:31 1...	FLOAT
_MG_0141.jpg	N31.20031854	E121.60313209	16.420	2018:07:31 1...	FIX
_MG_0142.jpg	N31.20031796	E121.60396117	16.286	2018:07:31 1...	FLOAT
_MG_0143.jpg	N31.20032387	E121.60535620	16.447	2018:07:31 1...	FIX
_MG_0144.jpg	N31.20032359	E121.60654665	16.296	2018:07:31 1...	FIX
_MG_0145.jpg	N31.20032435	E121.60725310	16.174	2018:07:31 1...	FLOAT
_MG_0146.jpg	N31.20032428	E121.60737382	16.226	2018:07:31 1...	FIX
_MG_0147.jpg	N31.20035721	E121.60795778	16.412	2018:07:31 1...	FLOAT
_MG_0148.jpg	N31.20067544	E121.60825685	16.219	2018:07:31 1...	FLOAT

Result (93/95) Fixed: 59, Float: 34, Single: 0, Other: 0

Close **PPK TXT** **ViewPlot**

Figure 6.8 Geotagged Result List

6.2.4 View processed results

After the geotag for the pictures is completed, the software automatically generates folders named 'geotag' and 'workingtemp' in the working directory, where the 'geotag' folder contains the pictures that have been tagged and ppk.txt file which indicates the information of the tagged pictures, and the 'workingtemp' folder contains the post-processing positioning results and the RINEX format file.

The coordinate information of the tagged pictures including latitude, longitude, altitude and position status can be seen by clicking the picture file name in Tersus GeoPix software. Whether the position status of the tagged picture is FIX or Float can also be seen in the ppk.txt file which locates in 'geotag' folder.

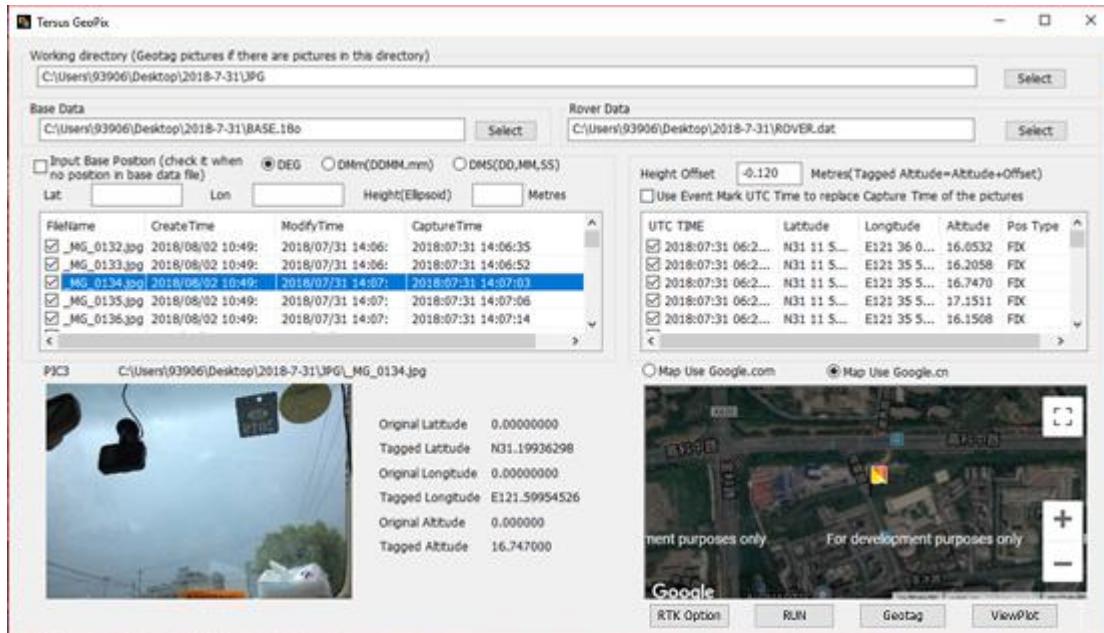


Figure 6.9 Check the coordinate information of the tagged pictures

ppk.txt - Notepad					
File	Edit	Format	View	Help	
_MG_0132.jpg	31.19821689421	121.60010726119	16.0532	FIX	
_MG_0133.jpg	31.19869818445	121.59984354075	16.2058	FIX	
_MG_0134.jpg	31.19936297992	121.59954526153	16.7470	FIX	
_MG_0135.jpg	31.19957362808	121.59944721363	17.1511	FIX	
_MG_0136.jpg	31.1997257214	121.59928046970	16.1508	FIX	
_MG_0137.jpg	31.20020024198	121.59919950245	16.1178	FIX	
_MG_0138.jpg	31.20029100948	121.59961425946	16.2408	FIX	
_MG_0139.jpg	31.20031335827	121.60059020252	17.4133	FIX	
_MG_0140.jpg	31.20031582509	121.60222545638	17.4892	FLOAT	
_MG_0141.jpg	31.20031853957	121.60313208929	16.4204	FIX	
_MG_0142.jpg	31.20031796453	121.60396116515	16.2867	FLOAT	
_MG_0143.jpg	31.20032387112	121.60535619851	16.4479	FIX	
_MG_0144.jpg	31.20032358755	121.60654665129	16.2964	FIX	
_MG_0145.jpg	31.20032435118	121.60725310181	16.1746	FLOAT	
_MG_0146.jpg	31.20032427759	121.60737382360	16.2269	FIX	
_MG_0147.jpg	31.20035720801	121.60795777639	16.4127	FLOAT	
_MG_0148.jpg	31.20067544105	121.60825685474	16.2197	FLOAT	
_MG_0149.jpg	31.20094709229	121.60842096045	16.1861	FIX	
_MG_0150.jpg	31.20148644347	121.60875465811	16.0410	FIX	

Figure 6.10 Information in ppk.txt file

Click [ViewPlot] at the bottom to view the positioning results of the GNSS post-processing data and the location information of the EVENT moments. The example is shown in Figure 6.10 and Figure 6.11. In the screenshots below, the position status of green points are fixed, the position status of yellow points are float.

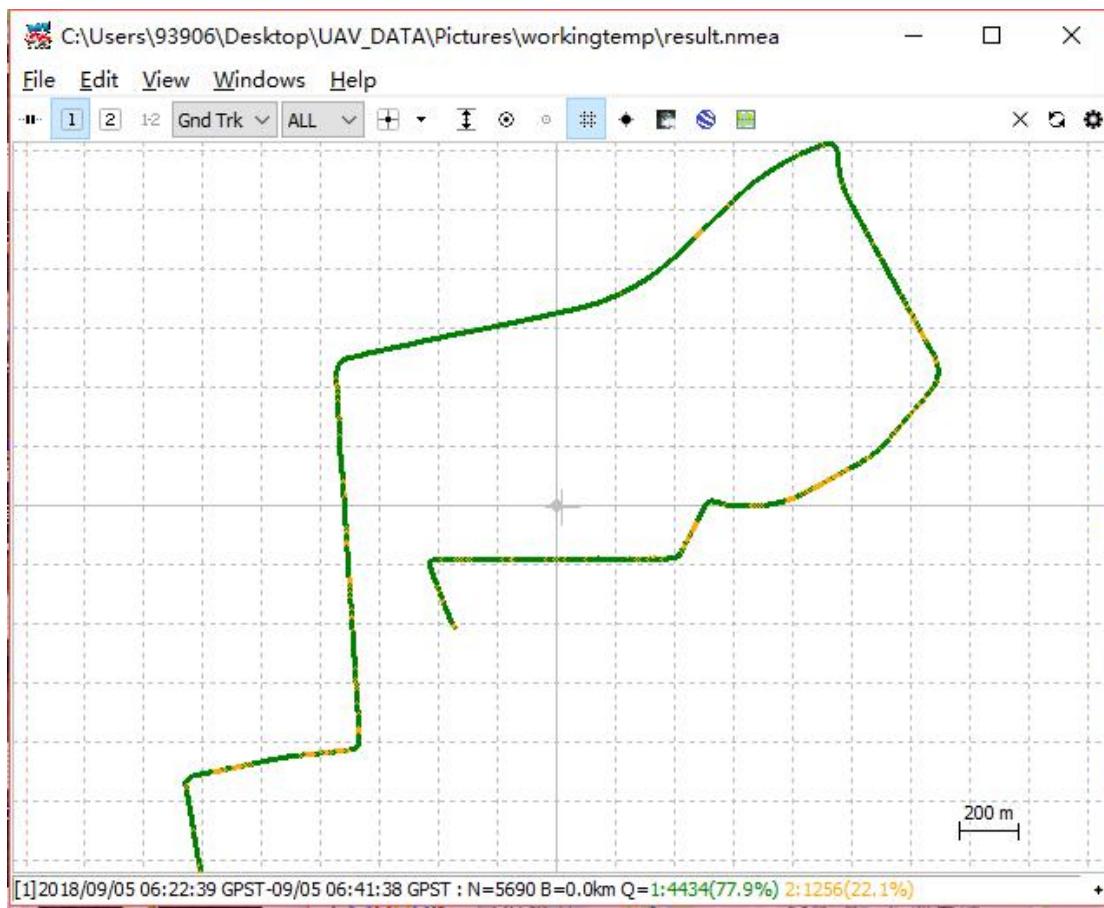


Figure 6.11 Positioning results of the GNSS post-processing

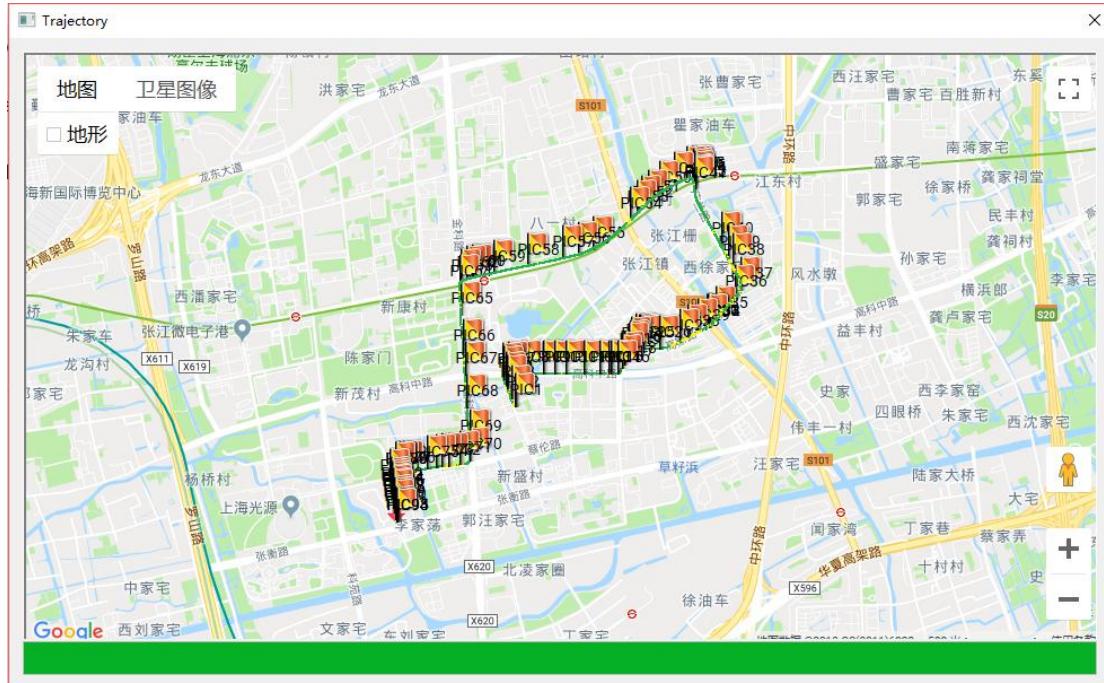


Figure 6.12 The location information of the EVENT moments

7. Terminology

BDS	BeiDou Navigation Satellite System
DC	Direct Current
eMMC	Embedded Multi Media Card
EXIF	Exchangeable Image File Format
GLONASS	GLObal NAVigation Satellite System
GNSS	Global Navigation Satellite System
GPS	Global Positioning System
PC	Personal Computer
PPK	Post-Processing Kinematic
PPS	Pulse Per Second
RINEX	Receiver Independent Exchange format
RMS	Root Mean Squares
RTK	Real-Time Kinematic
RTCM	Radio Technical Commission for Maritime Services
UAV	Unmanned Aerial Vehicle, drone
USB	Universal Serial BUS

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