

# Tersus GNSS

## David GNSS Receiver

### Overview

---

The Tersus David is a cost-efficient, palm-sized GNSS receiver designed for surveying, UAVs, AGVs, and agricultural applications. Working with an external GNSS antenna, the free Tersus Survey App and post-processing software, the David GNSS receiver is a low-cost solution for all survey applications, including real-time RTK positioning and data collection for PPK.

A 4GB in-built memory makes it easy to record data for post processing. The compact size, IP67-rated enclosure, and external Bluetooth module alleviates most of the inconveniences encountered in field work.



### Key Features

---

- ✓ Supports multi-constellation including BeiDou, GPS and GLONASS
- ✓ Supports 384 channels
- ✓ Supports RTCM2.x/3.x, CMR/CMR+ corrections
- ✓ Flexible for integration in different applications
- ✓ Data update rate up to 20Hz
- ✓ In-built 4GB storage benefits data collection
- ✓ IP67-rated dust- & waterproof enclosure, for reliability in challenging environmental conditions
- ✓ Supports Nuwa surveying software

**Website:** [www.tersus-gnss.com](http://www.tersus-gnss.com)  
**Sales Inquiry:** [sales@tersus-gnss.com](mailto:sales@tersus-gnss.com)  
**Technical Support:** [support@tersus-gnss.com](mailto:support@tersus-gnss.com)

Information is subject to change without notice.  
© Copyright 2023 Tersus GNSS Inc.

# Tersus GNSS David GNSS Receiver

## Technical Specifications

### Performance

Signal Tracking:		
GPS L1, L2;	GLONASS L1, L2;	BDS B1, B2
Channels:	384	
Single Point Positioning Accuracy (RMS):		
- Horizontal:	1.5m	
- Vertical :	3.0m	
Real Time Kinematic/RTK (RMS):		
- Horizontal:	10mm+1ppm	
- Vertical:	15mm+1ppm	
Initialization (Typical):	<10s <sup>(1)</sup>	
Initialization Reliability:	>99.9% <sup>(2)</sup>	
Post Processed Kinematic (RMS):		
- Horizontal:	10mm+1ppm	
- Vertical:	15mm+1ppm	
Static Post Processing (RMS):		
- Horizontal:	3mm+0.5ppm	
- Vertical:	5mm+0.5ppm	
Observation Accuracy (zenith direction):		
- C/A Code:	10cm	
- P Code:	10cm	
- Carrier Phase:	1mm	
Time To First Fix (TTFF):		
- ColdStart:	<50s	
- WarmStart:	<30s	
Re-acquisition:	<2s	
Timing Accuracy (RMS):	20ns	
Velocity Accuracy (RMS):	0.03m/s	
Differential Data Format:	RTCM 2.x/3.x, CMR/CMR+	
Data Output:	NMEA-0183, Tersus Binary	
Data Update Rate:	20Hz	
Storage:	In-built 4GB	

### Electrical

Input Voltage:	5~12V DC <sup>(3)</sup>
Power Consumption(at 25°C):	3.65W (David only)
Active Antenna Input Impedance:	50Ω

### Software Support

Tersus GNSS Center
Other third party software support NMEA-0183

### Communication

Serial Ports:	RS232 x2
Serial Baud Rate:	up to 460800bps
USB Port:	USB 2.0 Device x1
Antenna Connectors:	SMA Female x1

### Physical

Dimension:	104x65x31mm
Weight:	≈250g <sup>(4)</sup>

### Environmental

Operating Temperature:	-40°C~ +70°C
Storage Temperature:	-40°C~ +85°C
Humidity:	95% non-condensing
Dust-& waterproof:	IP67

### Optional Accessories

2W/28W 410-470MHz radio to transmit/receive RTK corrections
Battery bank

Note:

- (1) The initialization time depends on various factors, including the number of satellites, observation time, atmospheric conditions, multi-path, obstructions, satellite geometry, etc.
- (2) The initialization reliability may be affected by atmospheric conditions, signal multipath, and satellite geometry.
- (3) It is recommended using 2A instead of 1A when the external power is 5V.
- (4) The actual size/weight may vary depending on the manufacturing process and measurement method.