

# Tersus

# MetaVerse Painter Mobile Mapping System

## Overview

MVP is a mobile mapping system which can rapidly capture rich geospatial data while mounted on mobile platforms such as drones. As a cost-effective and high-precision mobile mapping application solution, it highly the high-performance GNSS-aided inertial navigation system (INS) and Tersus's patented GNSS receiver and supports RTK/PPK processing. MVP supports several LiDARs currently available in the market, such as Hesai, LIVOX, Velodyne, Quanergy, Ouster and RIEGL.

MVP is a complete solution provided by Tersus, including LiDAR, industrial-grade camera, mounting brackets, vibration isolator and other optional equipment, as well as LiDAR Calibration, Bore-Sighting, datalogging software and Tersus Engine supported automatic Post-Processing (PPK) and Point Cloud Processing software.

With massive high-precision 3D spatial data, high-density point cloud data and high-resolution panoramic image data, MVP can be widely used for terrain mapping, mine and water conservancy measurement and maintenance, agricultural and forestry surveying, power line inspections, and disaster emergency response, as well as smart cities, BIM modeling, urban streetscapes, transportation infrastructure measurements, etc.

## Key Features

- ✓ Dense point clouds (up to 1,920,000 meas./sec) and images
- ✓ 300m scan range
- ✓ Field of view 360°
- ✓ 5mm accuracy, 10mm precision
- ✓ Advanced GNSS RTK system and built-in IMU supported
- ✓ User-friendly mounting
- ✓ Lightweight (1.23kg with camera)
- ✓ Low power consumption
- ✓ Multiple platforms (Drone, Vehicle, handheld) supported
- ✓ Powerful one-click processing software



# Technical Specifications

## System Platform

|                        |   |
|------------------------|---|
| Weight                 | 0.87kg (without camera)                   |
|                        | 1.23kg (with camera)                      |
| Power Supply / Voltage | DC 9 ~ 36 V                               |
| Power Consumption      | 17 W without camera, 24W with Sony camera |
| Operating Temperature  | -10°C ~ +40°C                             |
| Storage Temperature    | -40°C ~ +85°C                             |
| Dust-&Waterproof       | IP64                                      |
| Data Storage           | 256GB USB, up to 1TB                      |

## Scanner Performance (based on Hesai Pandar XT32-M2X)

|                                 |  |
|---------------------------------|--|
| Laser Class                     | Class 1 Eye Safe                       |
| Wavelength                      | 905 nm                                 |
| Operating Principle             | TOF <sup>1)</sup>                      |
| Measurement Range               | 0.5 to 300 m                           |
| Field of View (Horizontal)      | 360°                                   |
| Horizontal Resolution           | 0.09° (5Hz)                            |
|                                 | 0.18° (10Hz)                           |
|                                 | 0.36° (20Hz)                           |
| Field of View (Vertical)        | 40.3° (-20.8° ~ +19.5° )               |
| Vertical Resolution             | 1.3°                                   |
| Frame Rate                      | 5 Hz, 10 Hz, 20 Hz                     |
| Returns supported               | Single Return (Last, Strongest, First) |
|                                 | Dual Return                            |
|                                 | Triple Return                          |
| Max. Effective Measurement Rate | 640,000 pts/ sec (single return)       |
|                                 | 1,280,000 pts/ sec (dual return)       |
|                                 | 1,920,000 pts/sec (triple return)      |
| LiDAR Accuracy/ Precision       | 10 mm / 5mm                            |
| Point Cloud Precision           | ±2.5 cm ( 5 m/s @ 50 m AGL)            |

Note: 1) Distance measurement: Time of Flight (TOF), distance to the object can be measured by calculating the time between laser emission and receipt.

## GNSS / IMU Performance

|                            |                     |
|----------------------------|---------------------|
| Positioning Accuracy (RMS) | 0.5cm+1ppm (PPK)    |
|                            | 1cm+1ppm (RTK)      |
| GNSS data rate             | Up to 100Hz         |
| IMU data rate              | Up to 2000Hz        |
| Roll & Pitch Accuracy      | <0.01° Pitch & Roll |
| Heading Accuracy           | <0.05° Heading      |

## Optional Accessories

|        |                   |
|--------|-------------------|
| Camera | RGB Camera (24MP) |
|--------|-------------------|

## Datasheet

|                     |                        |
|---------------------|------------------------|
|                     | Thermal Camera         |
| DJI Skyport Adapter |                        |
| Vibration Isolator  |                        |
| Antenna Mounts      | Aerial Mount for drone |
|                     | Vehicle Mount          |

**Website** | [www.tersus-gnss.com](http://www.tersus-gnss.com)

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